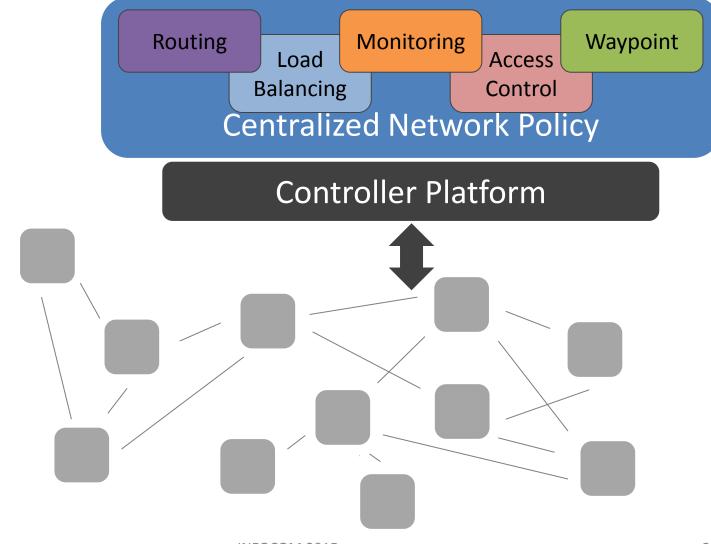
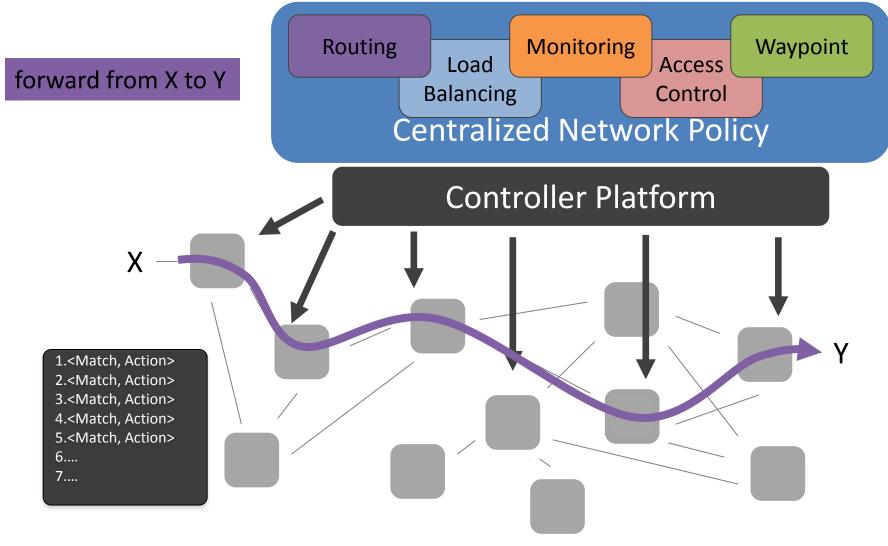
A Distributed and Robust SDN Control Plane for Transactional Network Updates

Marco Canini (UCL) with Petr Kuznetsov (Télécom ParisTech), Dan Levin (TU Berlin), Stefan Schmid (TU Berlin & T-Labs)

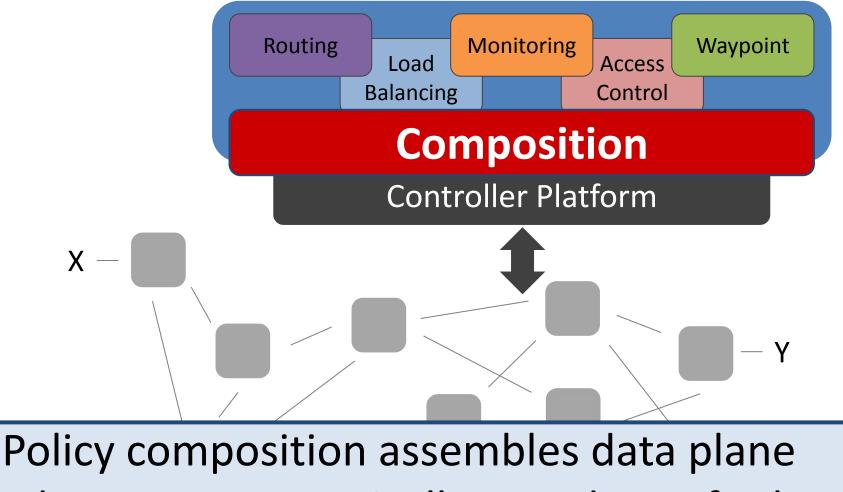
Network Policy Specification



Network Policy Specification



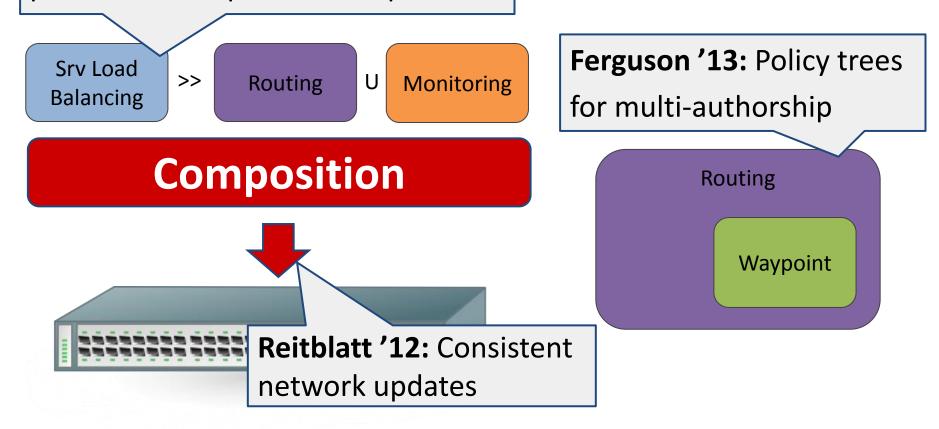
Network Policy Specification



updates as a semantically sound set of rules

Policy Composition Review

Foster '11, Monsanto '13: Modular, parallel and sequential composition



Conflicting Policies

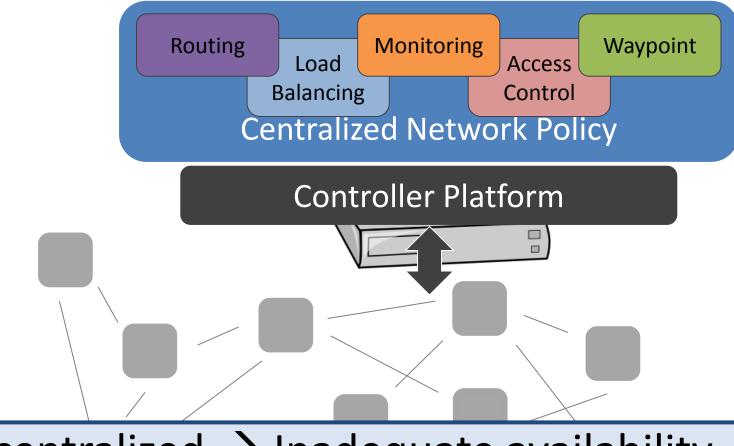


In the general case, policies might conflict Examples:

- Overlapping domains and same precedence
- Scarce flowtable resources

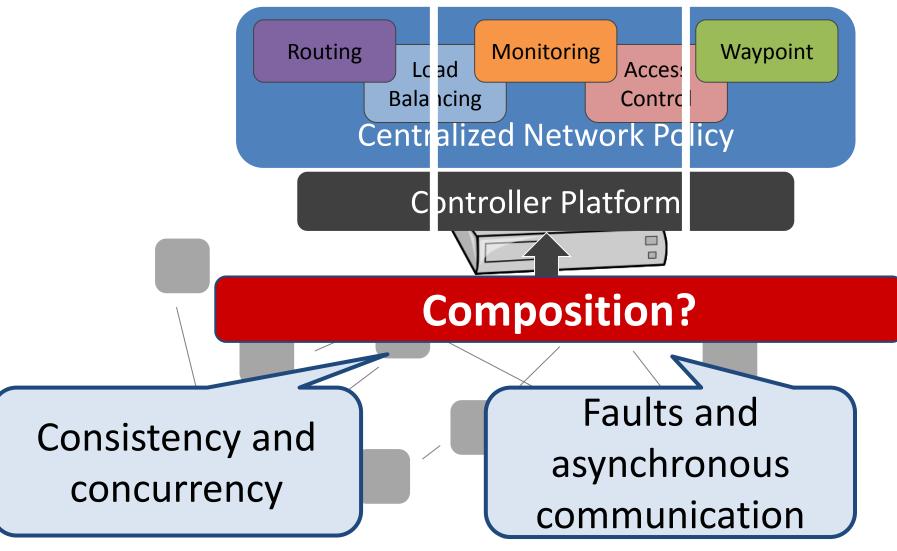
Goal: Must avoid conflicting policies!

Centralized Network Control?



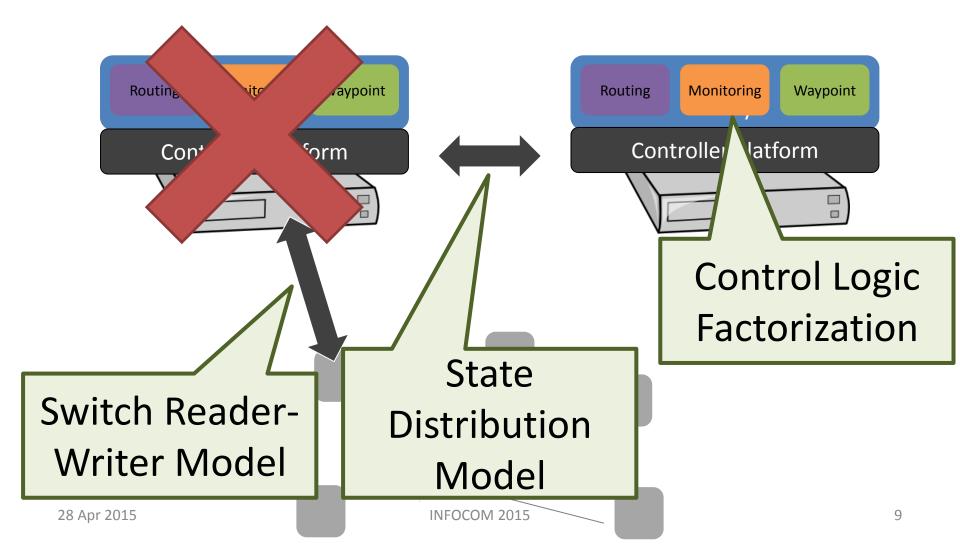
Fully centralized → Inadequate availability, scalability and responsiveness

Distributed Network Control



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Now, consider policy composition in the distributed control plane...

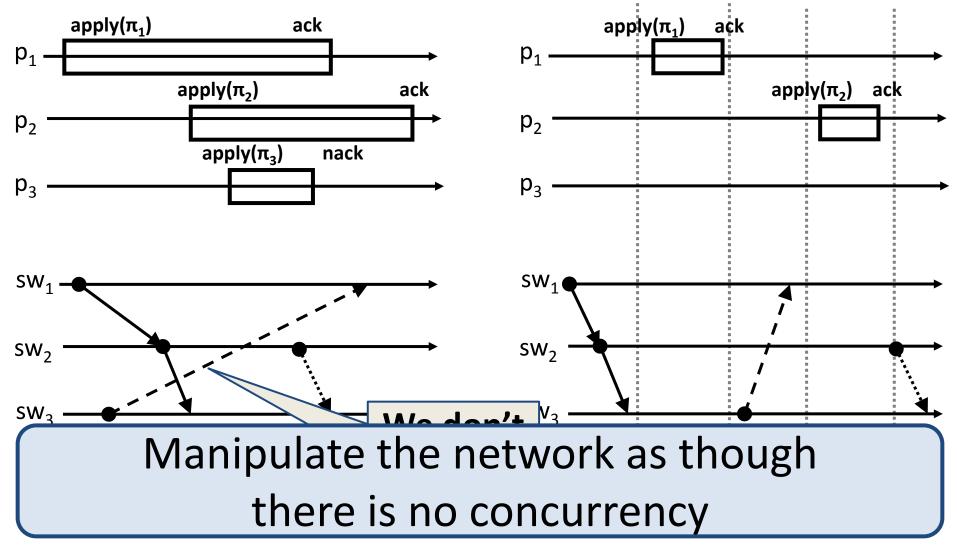


Why should the programmer care?

- We believe the programmer should not!
- Enter Software Transactional Networking
 - Let a dedicated component implement a general solution to all hard-to-solve, low-level concurrency and fault tolerance issues to policy composition

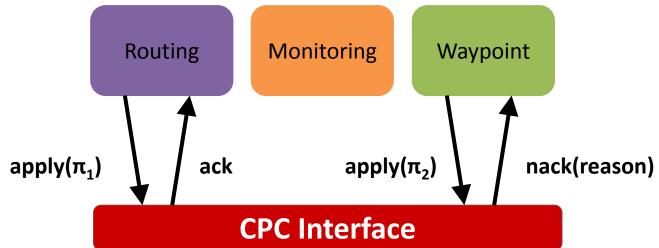


Consistency: Linearizability of updates



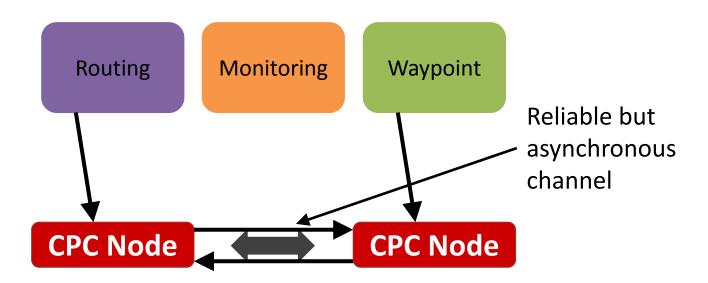
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Software Transactional Networking: Consistent Policy Composition (CPC)

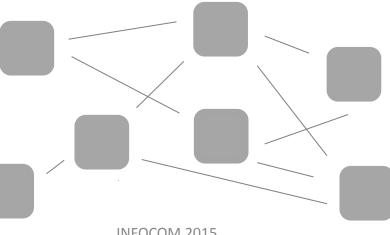


- 1. All-or-nothing semantics
- 2. Tolerate up to **f** controller node crash failures
- 3. Non conflicting policies eventually installed and at least one policy commits (among conflicting ones)
- 4. Ensure policy updates affect traffic as a sequential composition of their policies

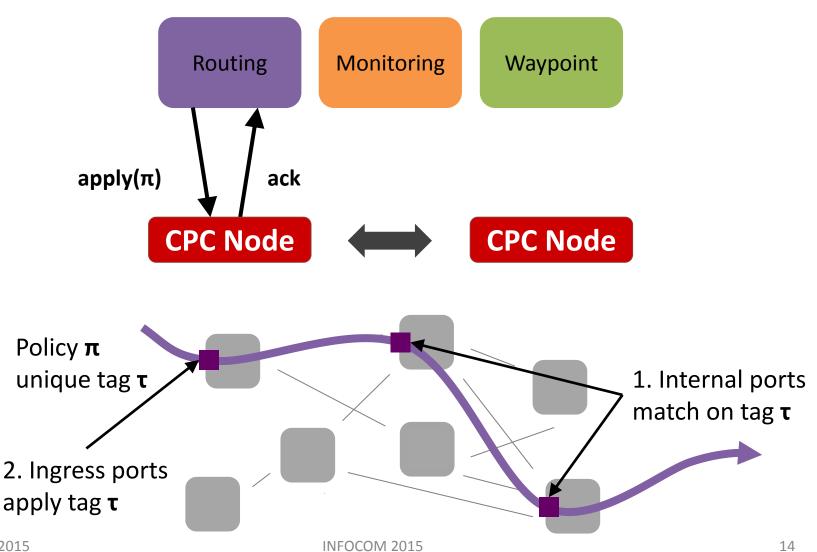
Conceptualizing CPC



Every controller node receives and participate in installing every policy update

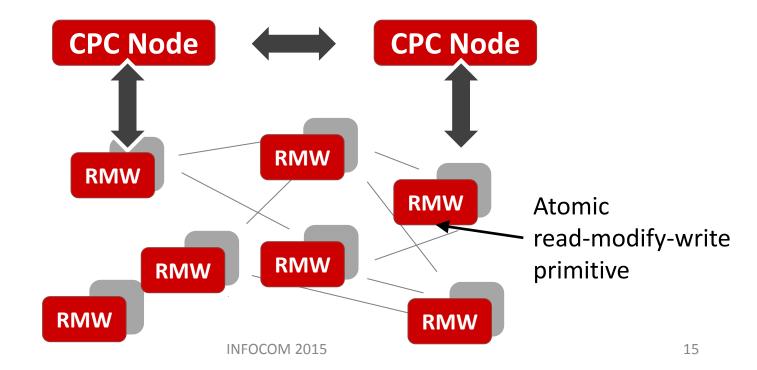


Conceptualizing CPC



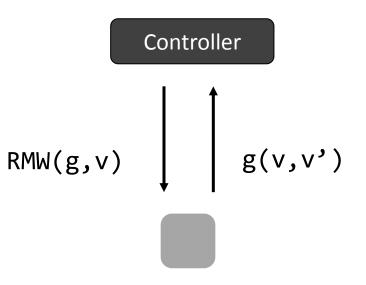
Conceptualizing CPC





RMW model

- Controllers access ports with atomic read-modify-write primitive RMW(g,v):
 - read current state v'
 - apply and return g(v,v')
- Intuition: do not update if policy update conflicts with currently installed policy
- In the paper: Theorem: 1-resilient read-write CPC is impossible



FixTag: upper bound algorithm

Operation:

- 1. Unique tag per path
- 2. Broadcast policy π to all other controllers
- 3. Update ingress ports in predefined order
- 4. ... add rule to tag all packets matching dom(π) with the tag corresponding to the path $\pi^{(i)}$ for ingress port i

Upsides: wait-free (tolerates all failure patterns)

Controllers only synchronize through the data plane

Downsides: tag complexity linear in # possible policies and paths

May grow super-exponential in the size of the network

Can we lower the tax complexity?

- No, if we get no feedback from the network
 - Tag τ cannot be reused if a packet tagged with τ is still "in flight"
- Suppose, we can correctly evaluate the set of active tags
 Correct (but asynchronous) oracle
- Single-controller scenario: one bit is enough!
 - Upon policy update π_i , wait until (i mod 2)-traffic is over, and use tag i mod 2
- Two or more controllers: inherent price of concurrency?
 - Between constant and super-exponential?
- Yes, if controllers coordinate the use of tags

ReuseTag: linear complexity

- Proportional to the level of resilience:
 - Up to f failures: f+2 tags needed (proved optimal)

 Controllers use replicated state machine that imposes a total order on the policy updates and ensures coordinated use and reuse of tags

- All requests are serialized, even non-conflicting ones

Summary

- Software Transactional Networking framework for consistent policy composition (CPC) in distributed SDN control planes
 - Transactional interface to manipulate the network as though there is no concurrency
 - Policies compose or conflict (and abort)
 - Formal model of the problem is in the paper
- Two CPC algorithms
 - FixTag
 - ReuseTag: f+2 tags (minimal number)

Backup

Acknowledgements



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